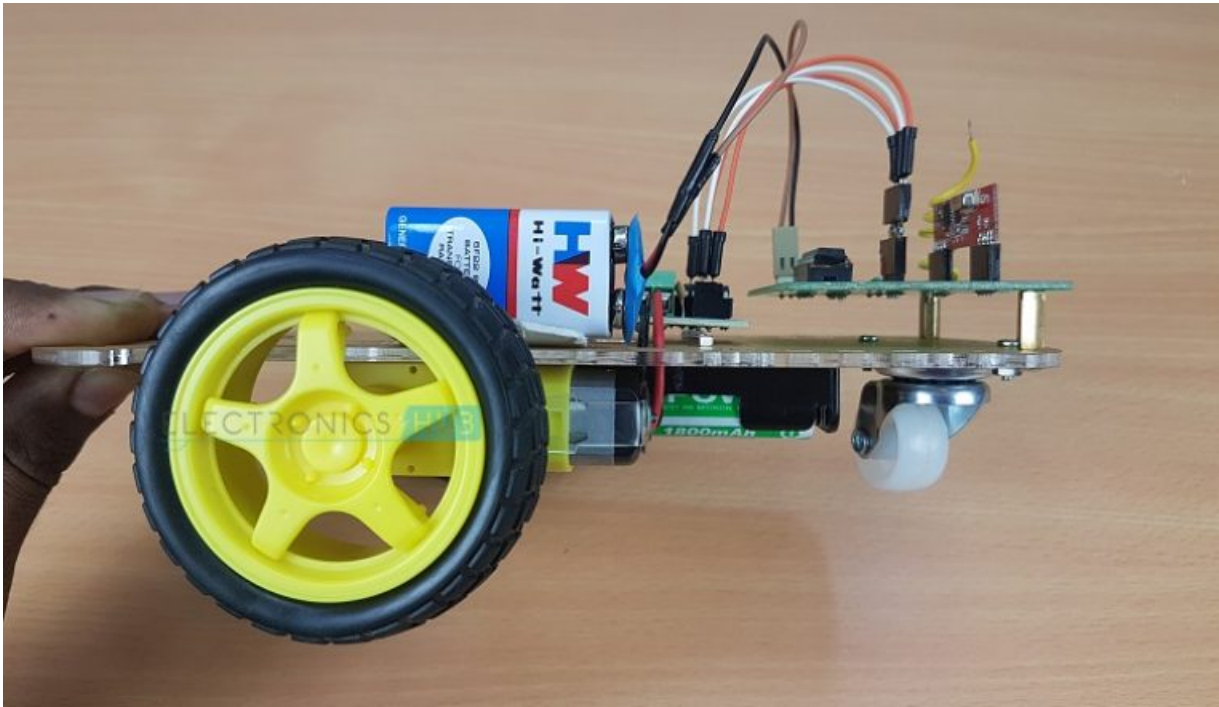


SERIAL COMMUNICATION CONTROLLED VEHICLE



The main purpose of this project is to develop a remote user interface to control a robot via a wireless technology. There is a need to communicate the robot remotely in order to control the robot movements we are passing the critical data both ways.